



# SWITCHWELD COBOT WELDING

- AND -

# SCA TRAINING PROGRAM UPDATES



switchweld.com

# OUTLINE

## SWITCHWELD-

Collaborative welding robot available through AUBO Robotics USA

- [Switchweld.com](http://Switchweld.com)

## SCA COLLABORATIVE WELDING ROBOTIC TRAINING PROGRAM-

- Courses available
- Course Structure
- Implementation
- Early Feedback





# SWITCHWELD SYSTEM OVERVIEW

The SwitchWeld is a collaborative Welding Robot that uses the AUBO Robotics i-series arms to create a turnkey solution to welding automation.

There are 4 SwitchWeld Products-

- SwitchWeld Basic
- SwitchWeld Plus
- SwitchWeld Reach
- SwitchWeld Plasma



Figure - The SwitchWeld Plus Plug -and-Play system



# SWITCHWELD FEATURES

## SWITCHWELD COMMON FEATURES

- Teach Pendant
- Welding Torch and Torch Holder
- Welding Table
- Fixturing
- 6 DOF
- Free-Drive by Hand
- Optional Magnetic Base
- 7th Axis Rail

## SWITCHWELD EXCLUSIVE FEATURES

- Precision Joystick
- Arc-Advisor



1.

Precision  
Joystick

2.

Magnetic  
Base





# SWICTHWELD CUSTOMERS

## EXAMPLE APPLICATIONS

- Pipe Welding
- Fence & Gate Fabrication
- Structural Bracket Welding
- Automotive & Trailer Frame Welding
- Tooling & Fixturing Fabrication



**Industry: Industrial Fencing**  
**Role: CEO**

“

This investment is not just about boosting productivity; it's about empowering our team to push the boundaries of what's possible and continue delivering top-notch quality to our clients. Together, we're forging a brighter, more innovative future.

”





# SCA COLLABORATIVE ROBOT TRAINING PROGRAM

- Led by Pat Cahill and team
- Developing multi-course curriculum
- Unique Features:
  - ✓ One course covering all major collaborative welding systems
  - ✓ Focus on applications and needs of shipyards, their suppliers, and related industries
  - ✓ Hands -on (2:1 hands -on time to lecture instruction)
  - ✓ Leave Qualification -Ready (Qualified in the future)



# TRAINING MODULES

**Training Module 1** - Collaborative Robot Operations: Provides the fundamentals of programming and working with Cobots including Safety, Terminology, and Basic Operations. 6 hours of instruction performed online plus 1hr examination online.

**Training Module 2 and 3** - Collaborative Robotic Welding I and II: Provides the fundamentals of programming weld operations with CoBots covering the following topics:

- 1.Safety Refresher
- 2.Terminology Refresher
- 3.Basic Operations Refresher
- 4.Robot motion, programming
- 5.Motion, linear, circular, other curves, weaving
- 6.Power supply control/communication, end conditions
- 7.Welds: 1G,2F,3F, plate and pipe, transitions (downhill, uphill)

Delivered at the SCA training center, 40 hours of instruction including lecture, lab and examination. 8 hrs of the time is dedicated to classroom instruction, and 24 hours dedicated to hands-on training in the CoBot Lab on CoBot equipment, 6 hours of qualification tasks.

**Training Module 4** - Collaborative Robotic Welding IV: Advanced applications and maintenance (will; be offered in the future)



# COURSE STRUCTURE & CONTENT

## TOPICS COVERED

- Using a cobot
  - Cobot Information
  - Errors
  - Movement
- Working With a Welding Cobot
  - Safety
  - Power on/off
  - Teaching the Cobot
  - Creating a Program

## TABLE OF CONTENTS

- Topic 1 - CoBot Welding System Safety (review)
- Topic 2 – CoBot Welding System Overview (review)
- Topic 3 - Collaborative Robot Motion (review)
- Topic 4 - Power Up / Down CoBot System
- Topic 5 - CoBot User Interfaces
- Topic 6 - Errors
- Topic 7 - Creating a Welding Program
- Topic 8 - Motion Paths Associated with Welds
- Topic 9 - Running a Welding Program
- Topic 10 - Editing a Welding Program
- Topic 11 – Welding with a CoBot System
- Topic 12 - Welding Qualification Readiness
- Topic 13 - Other Program Functions
- Topic 14 - Practical Considerations
- Topic 15 - Managing Program Files





# LAB STRUCTURE/CONTENT

## Motion labs:

- D1-1 Robot Intro, Jog Robot
- D1-2 Program the Robot I: Basics

## Horizontal Fillet labs:

- D1-3 Program the Robot II: programs for welding (no arc): Straight horizontal fillet (2F)
- D1-4 Program the Robot II: programs for welding (no arc): Wrap – outside corner (2F-2F)
- D1-5 Program the Robot II: programs for welding (no arc): inside corner (2F-2F)
- D2-3 Welding Straight horizontal fillet (2F)
- D2-4 Welding Wrap outside corner (2F-2F)
- D3-1 Welding Wrap inside corner (2F-2F)
- D3-6 Welding: Lap weld

## Groove labs:

- D1-3 Program the Robot II: programs for welding (no arc): Straight Groove (1G)
- D1-3 Straight Groove with multipass (1G)

## Circular labs:

- D2-2 Program the Robot II: programs for welding (no arc): circular, 360 deg. horizontal fillet (2F)
- D3-3 Welding circular, 360 deg. horizontal fillet (2F)

## Vertical Fillet Labs:

- D2-1 Program the Robot II: programs for welding (no arc): vertical fillet with weave (3F)
- D3-2 Welding vertical fillet with weave (3F)

## Advanced positions:

- D3-4 Welding Wrap (3F-2F)
- D3-5 Welding Inside Corner (2F-3F)

## Advanced labs:

- D4-2 Practical Considerations II: Troubleshooting a program
- D4-3 Practical considerations I: Defining Tool Center Point (TCP)
- D5-2 Weld Qualification readiness fillet in plate
- D5-4 Weld Qualification readiness Fillet in pipe

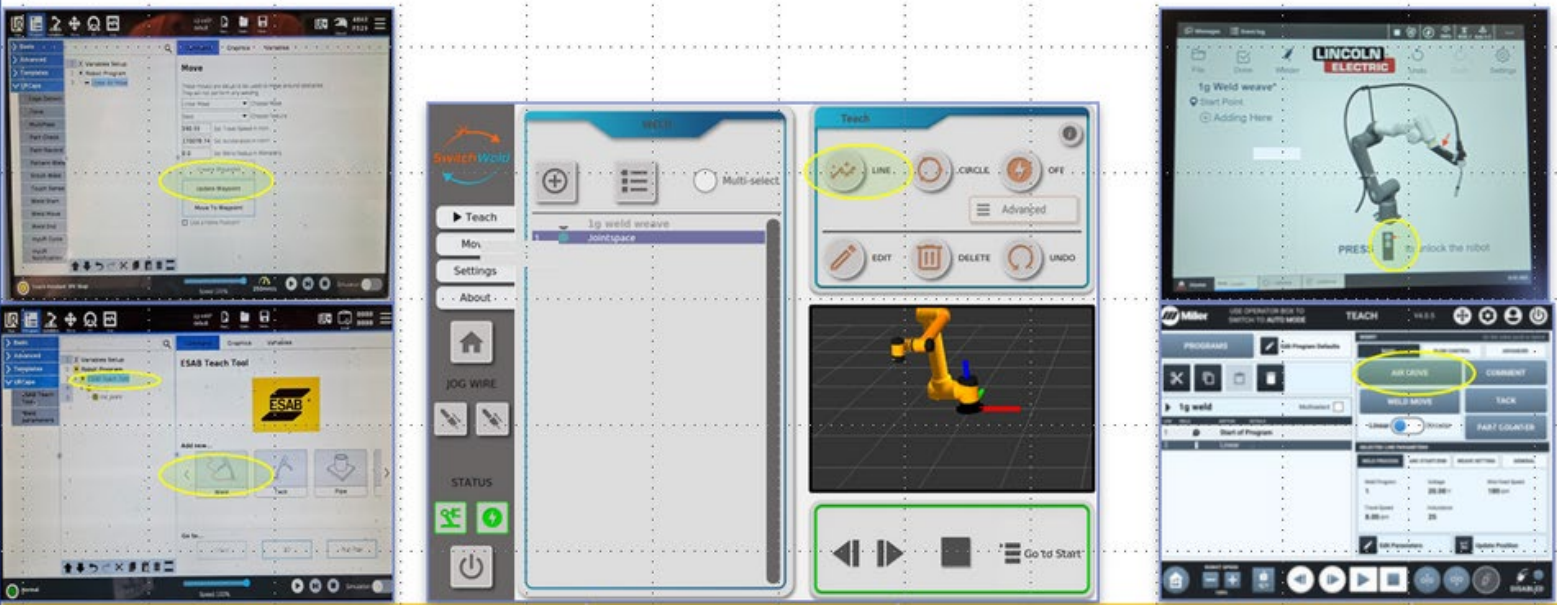


# SCREEN GRABS OF LECTURE CONTENT

Shipbuilding CoBot Alliance – Topic 8

## STRAIGHT LINE WELD – FIRST PROGRAM POSITION

- Select Line from the teach pendant (as shown below)
- Choosing Line means the upcoming move is a straight line

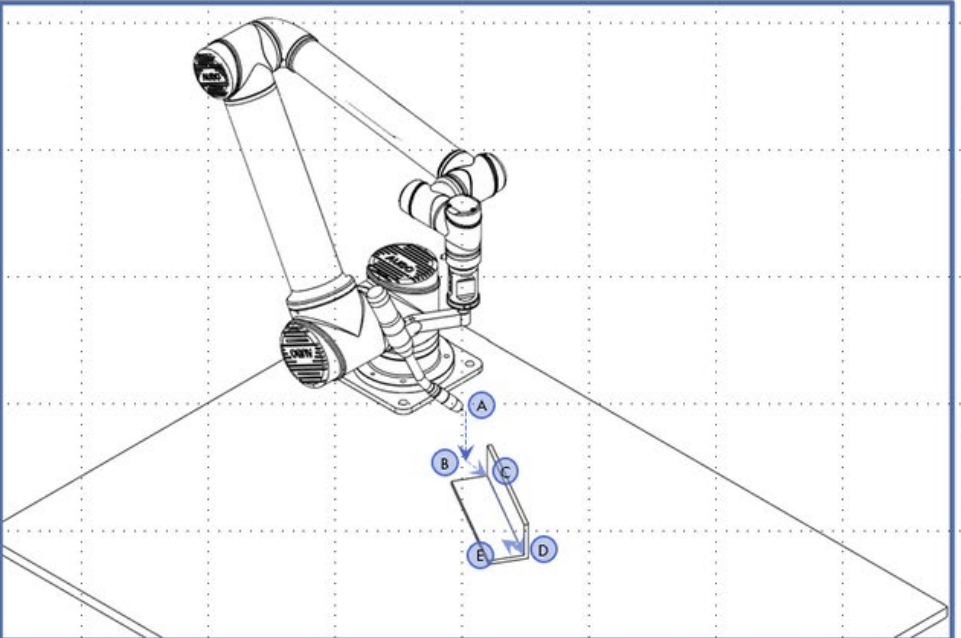


SCA Topic 8 – Motion Paths Associated with Welds6/6/2025©Robotic Technologies of Tennessee11

Shipbuilding CoBot Alliance – Topic 8

## HOME POSITION

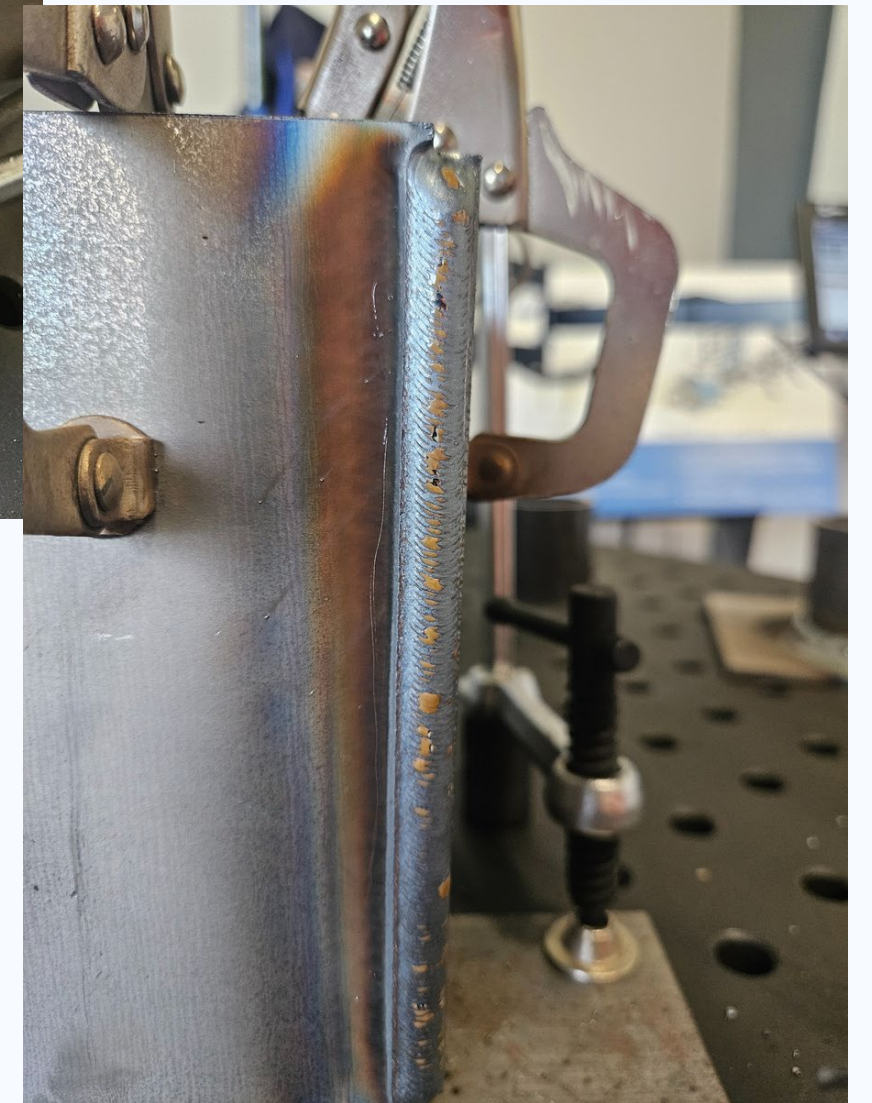
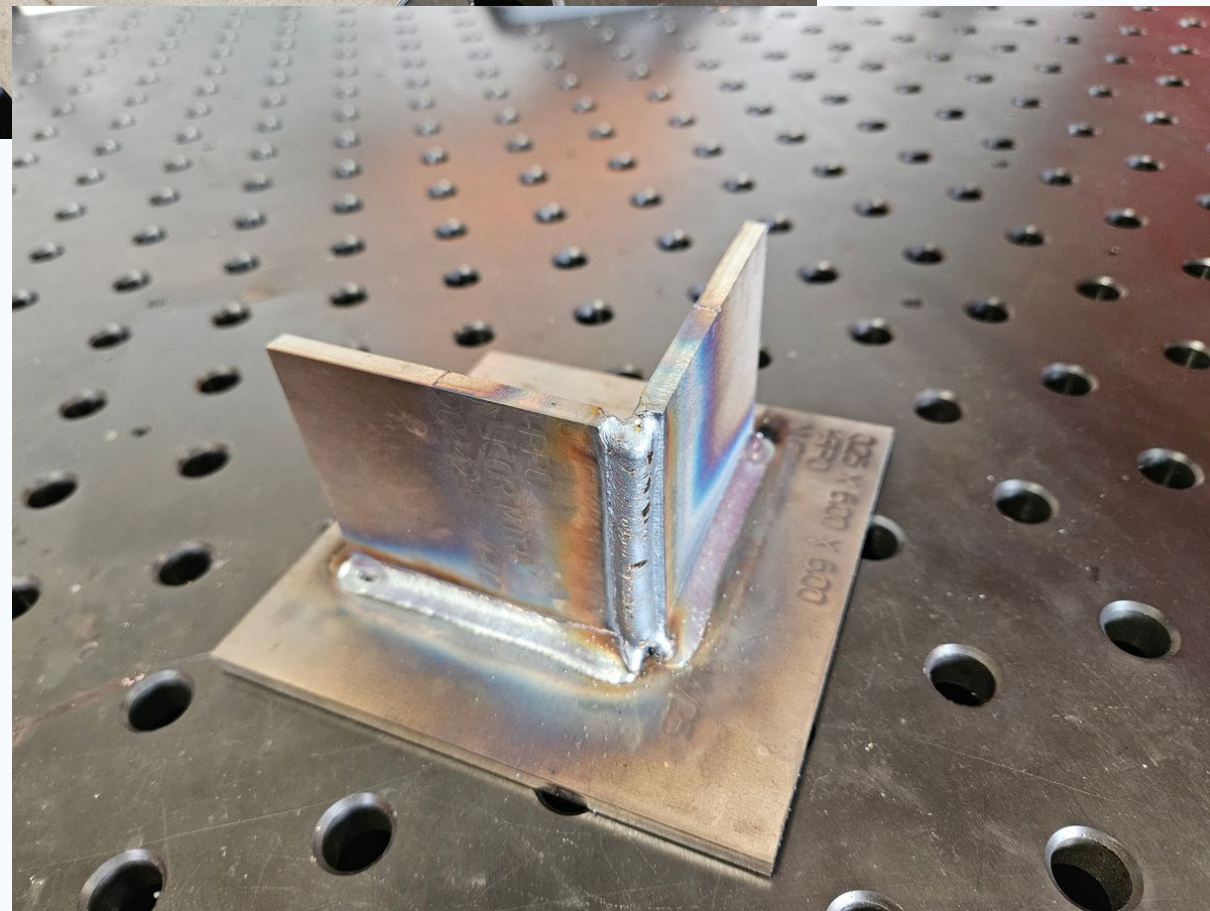
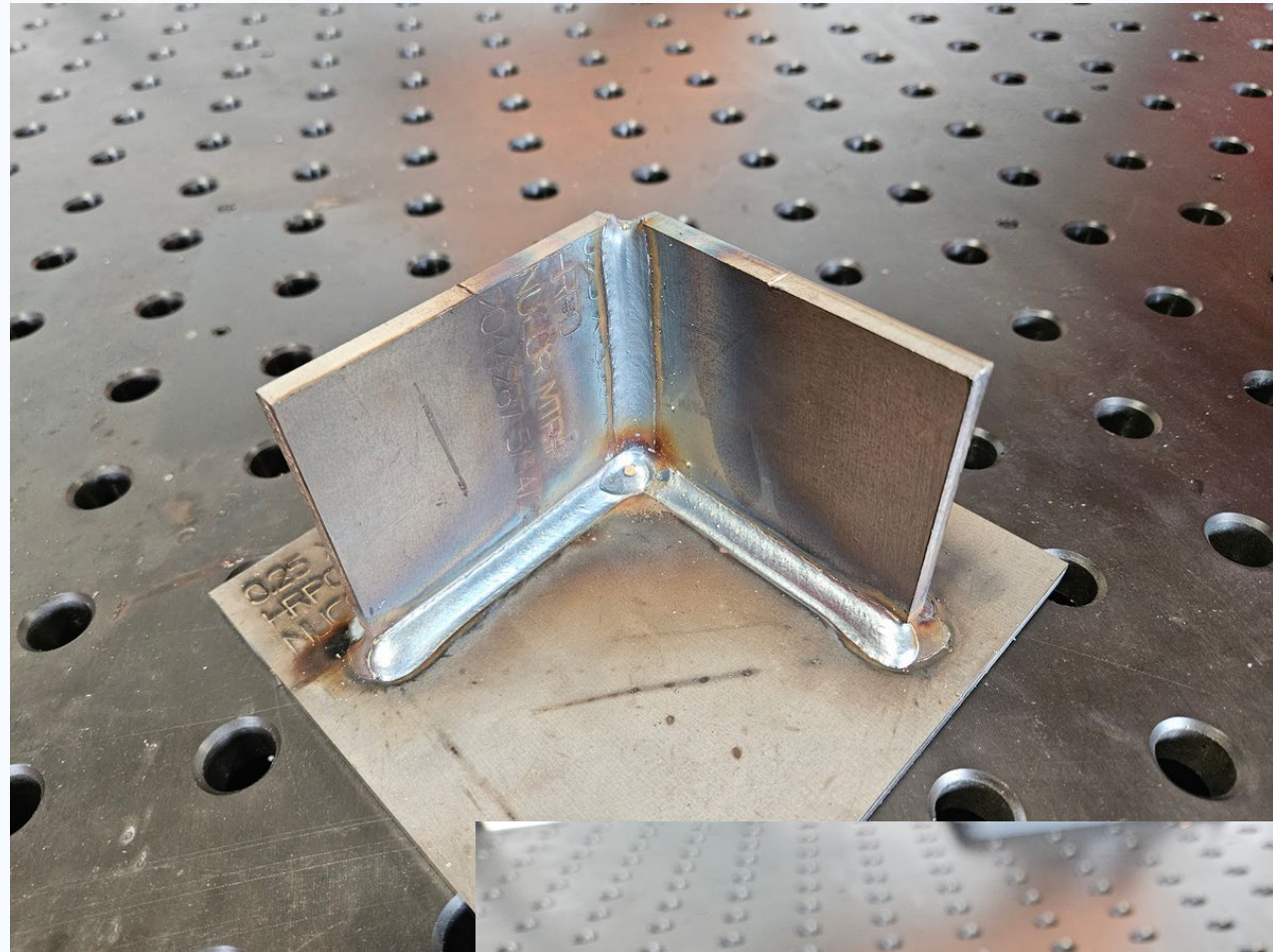
- The home position is a location of the robot out of the way of the work area but close to the job to minimize time moving to and from the work
- For convenience, you can begin and end every weld with the home position



SCA Topic 8 – Motion Paths Associated with Welds6/6/2025©Robotic Technologies of Tennessee5



# PHOTOS OF LABS





# SCA COURSE IMPLEMENTATION

- Feedback training - May - Tabet, NWTC
- Train the trainer trainer - June (2-6) - Tabet
- First training cohort (lead instructor Koryne Andrews) - June (23 - 27) - Tabet
- Ongoing training on regular basis
- Train the trainer trainer – September (exp) - NWTC
- First training cohort at NWTC (lead instructor James ..) - September (exp) – NWTC
- Ongoing training on regular basis





# TRAINING COURSE- EARLY FEEDBACK

It seems that the students were **overall very pleased** with the course and found it very useful. (see student attached reviews). The majority rated the course **clear/very clear** and all rated the lab sessions as covering the right amount of material. Students made some suggestions for future additions. Our observations are that **they all left well qualified** to independently use any of these systems with high expectation of success, as desired.



## End of Course Survey – Cobot Welding Training

Thank you for participating in our Cobot Welding course. Your feedback is essential to help us improve future sessions. Please take a few minutes to complete this short survey.

### 1. How would you rate the length of the course?

(Please select one)

- Too short
- ☒ Just right
- Too long

Optional comment:

### 2. How clearly presented was the course material?

(Please rate on a scale from 1 to 5)

- 1 – Not clear at all
- 2 – Somewhat unclear
- 3 – Neutral
- ☒ 4 – Mostly clear
- 5 – Very clear

Optional comment:

### 3. Do you think the lab sessions covered enough realistic weld positions?

- ☒ Yes
- No

If no, please explain:

### 4. Are there any specific weld positions you would like to see added in future courses?

N/A



# PHOTO OF CLASS







# QUESTIONS?

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CONTACT INFORMATION:



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