

# NSRP Robotic Arc DED AM – Advanced Capabilities Workshop

## Robotic DED Test-beds for Collaboration



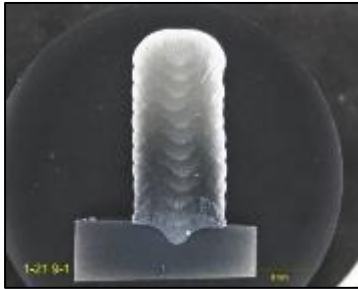
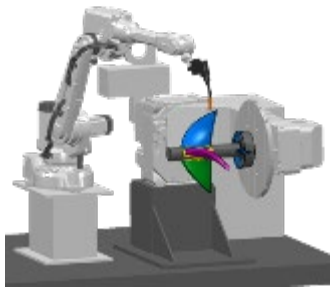
Dennis Harwig, EWI  
Senior Tech. Leader

# Acknowledgement

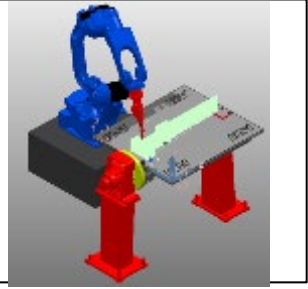
- Much of the content presented was developed in the National Shipbuilding Research Program – Advanced Shipbuilding Enterprise (NSRP-ASE) Research Announcement (RA) Project 2019-375-004.



# NSRP Robotic Arc Directed Energy Deposition (DED) Additive Manufacturing (AM) for Shipbuilding

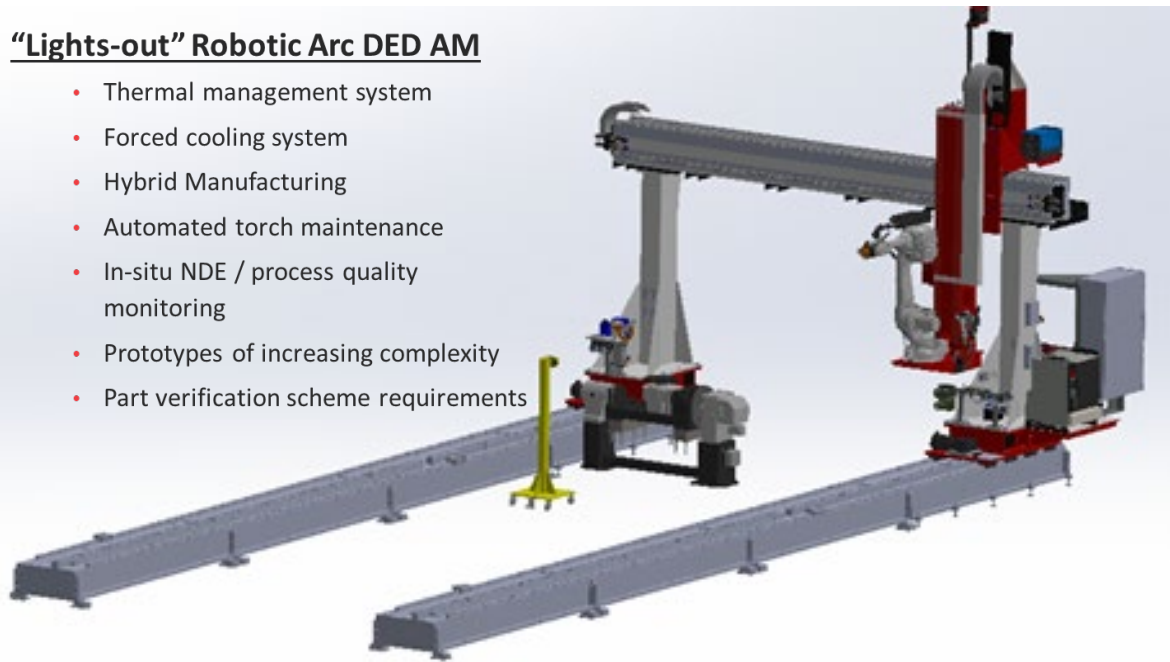


**Project Team**  
EWI – Project PI  
Navus Automation  
Austal USA  
NSWCCD  
ABS



## “Lights-out” Robotic Arc DED AM

- Thermal management system
- Forced cooling system
- Hybrid Manufacturing
- Automated torch maintenance
- In-situ NDE / process quality monitoring
- Prototypes of increasing complexity
- Part verification scheme requirements



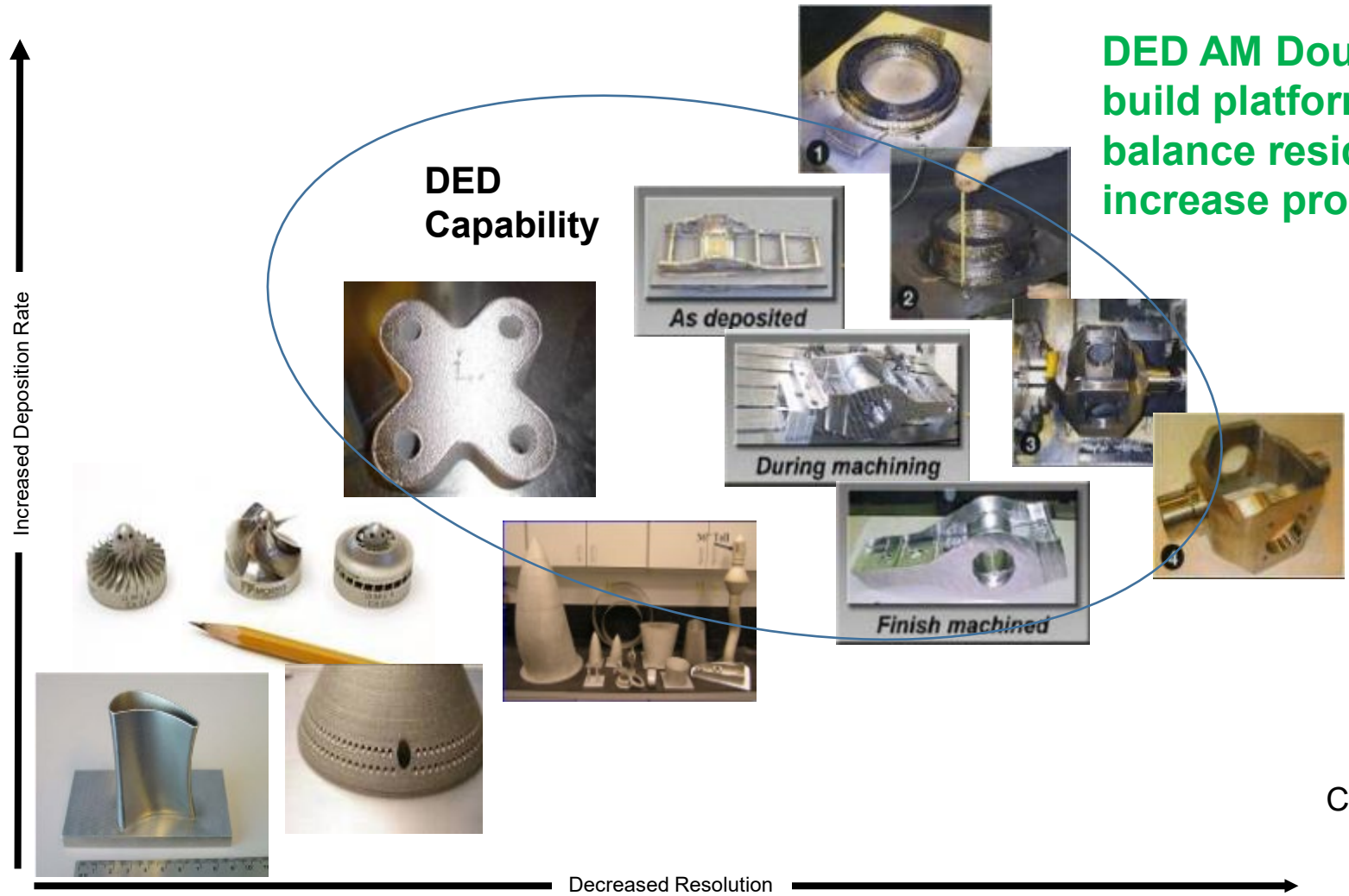
## **Objectives:**

- **Convert multiple robotic weld systems to DED systems**
- **Design standardized large-scale gantry DED system**
- **Develop digital data workflow processes**
- **Develop advanced training materials - workforce**
- **Demonstrate representative qualifications**
- **Provide standardized equipment & services**
- **Build prototypes of increasing complexity**
- **Identify implementation opportunities**

*Reducing barriers to implement DED AM*

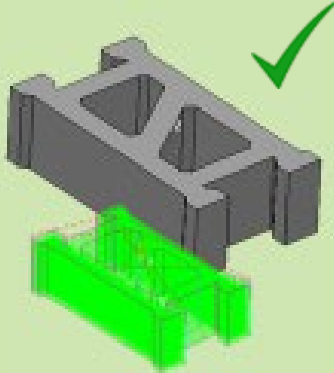

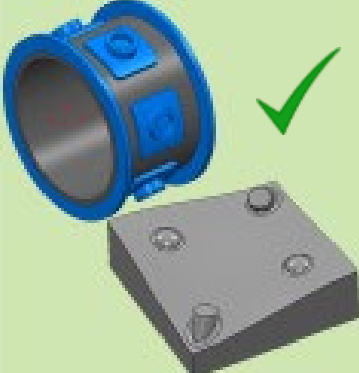
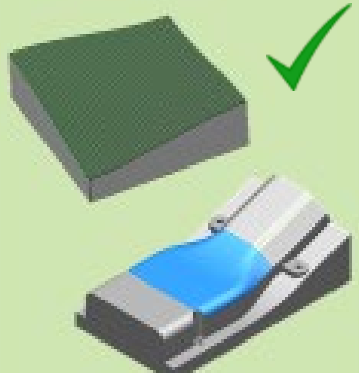

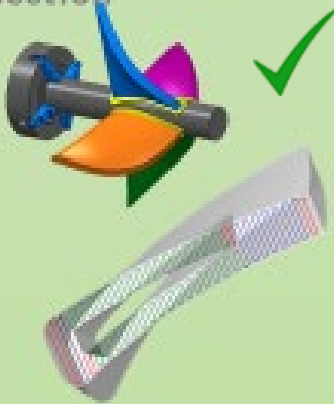




Project Period: June 2019 – July 2021

# DED Deposition Rate vs Resolution



Courtesy Boeing

# Autodesk PowerMill Additive – DED Build Categories

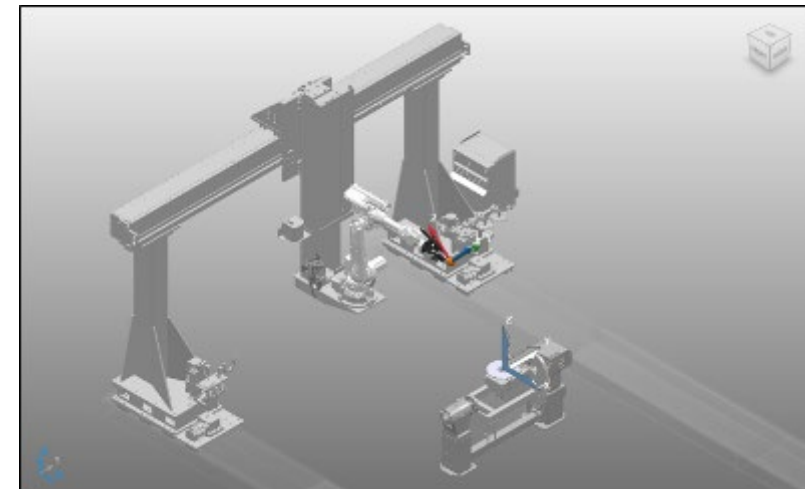
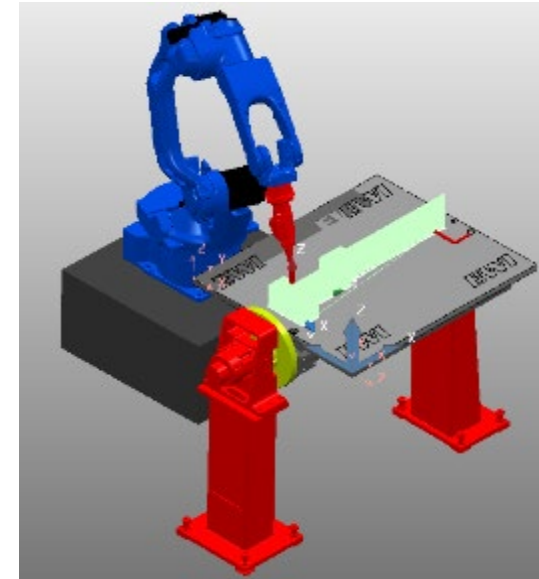
<p>1 – Linear 2.5D extrusions – walls and bricks</p> 	<p>2 – Surface of revolution – buckets</p> 	<p>3 – Features – on cylinders, planes and arbitrary bases</p> 	<p>4 – Surface coating – patches and single layers</p> 	<p>5 – Coaxial features – 360deg</p> 
<p>6 – Blades and blisks – varying X section</p> 	<p>7 – Multi axis sweep – varying X section tubes</p> 	<p>8 – Non adaptive repair</p> 	<p>9 – Adaptive repair</p> 	<p>10 – Artisan</p> 

\*Courtesy Autodesk

# Robotic DED Training & Build Test-beds

- Basic & Adv PowerMill DED AM Launched
  - Autodesk Authorized Training Center (pending)
- Multiple test-bed systems - training, process, prototyping
  - IR-based preheat & inter-pass control
- Robot DED AM systems available
  - 7-axis Motoman Fronius Arc DED System
  - 8-axis Motoman Powder Laser DED System
  - (2) 8-axis OTC Arc DED Systems\*
  - Dual 8-axis Genesis Fanuc MP-Arc DED System
  - 9- & 11-axis Navus ABB MP-Arc DED Gantry
- Additional robotic DED AM systems planned
  - 9-axis Cloos MP-Arc DED System\*
  - 6-axis Motoman Wire Laser DED System

\* Shared EWI/OSU Systems (MP) Multi-process / torch changer





# Robotic Arc DED Systems

**Fanuc - Fronius & SBI  
(CMT/GMA-P & Plasma)**



**Navus ABB Gantry  
(Multi-process DED)**



**Motoman - Fronius  
CMT/GMA-P/GMA**



**Fanuc - Lincoln  
GMA-P/GMA/TW-GMA**



**OTC-Daihen  
SyncroFeed**



**OTC-Daihen  
GMA-P/GMA**

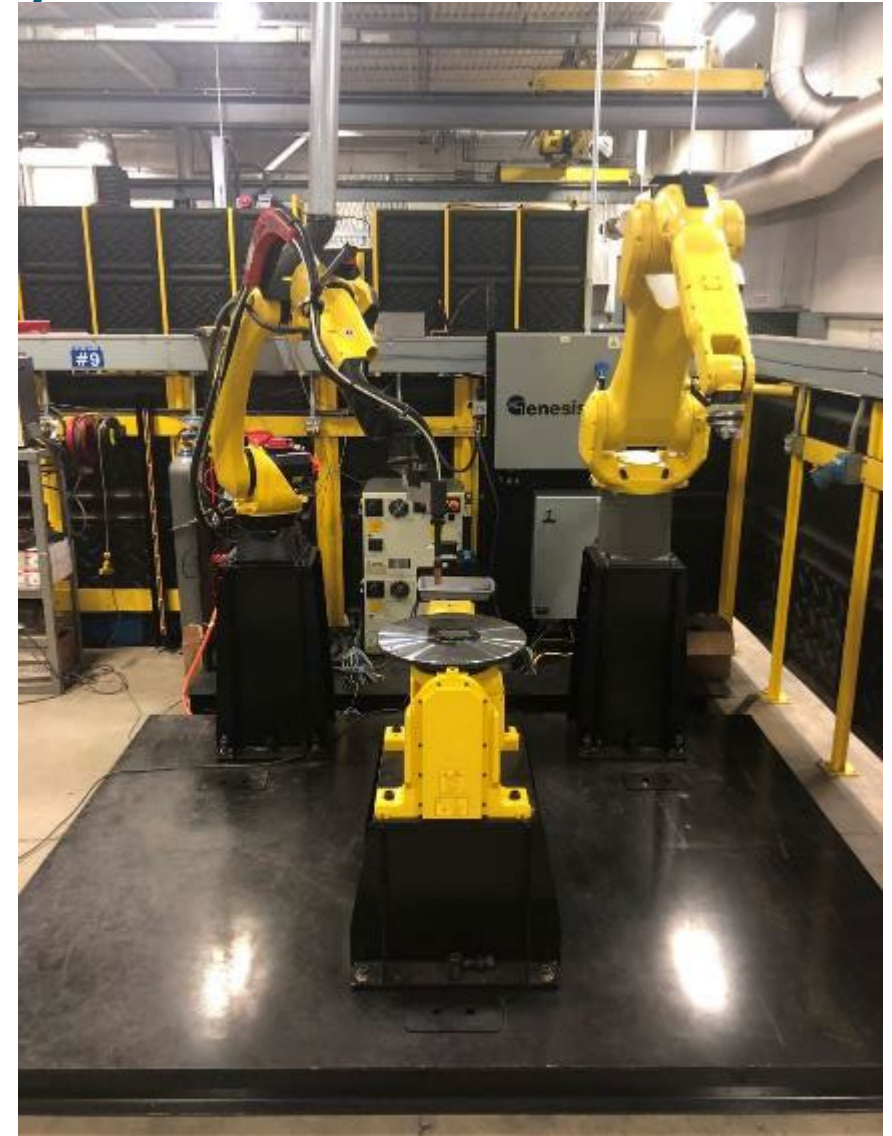


**Cloos  
Motion / GMA-P & T-GMA**



# Genesis / Fanuc Robotic Arc DED System

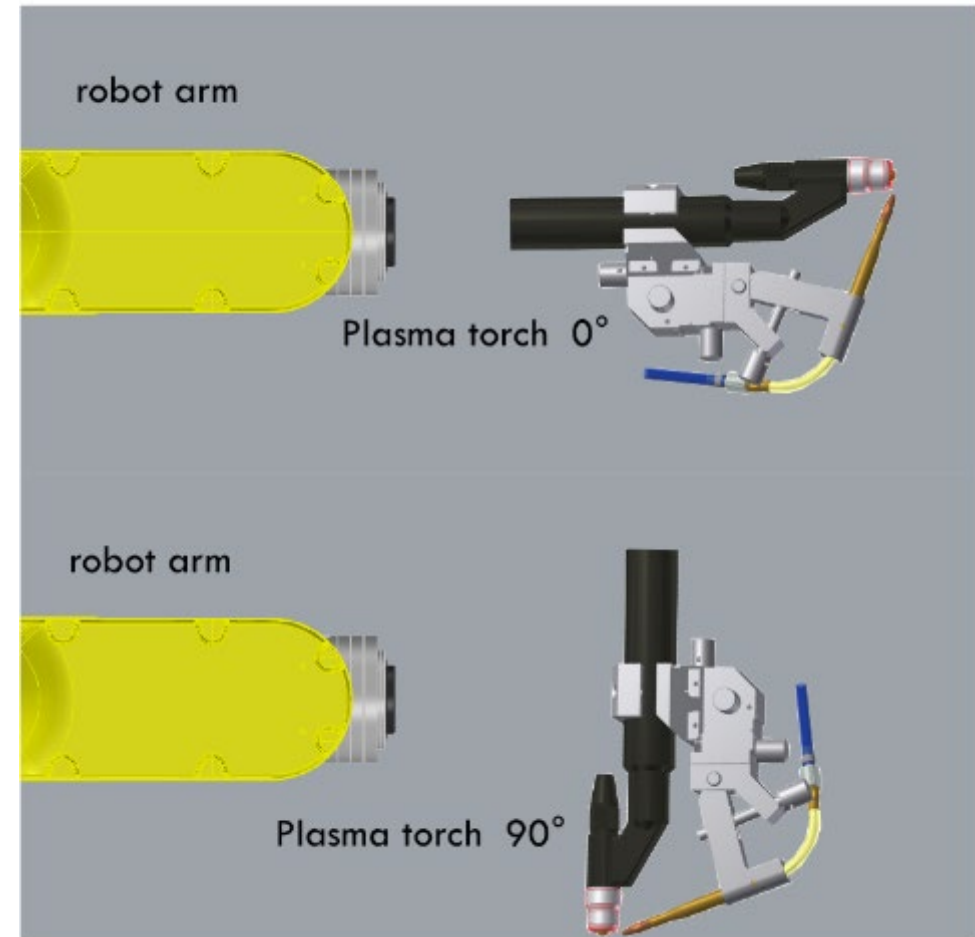
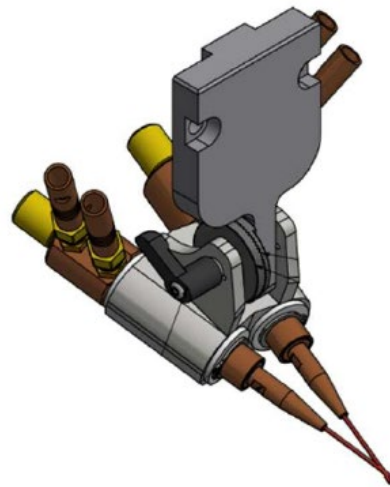
- Dual-arm system
  - Primary welding deposition arm
    - Fronius TPS 5000CMT
      - CMT, GMA-P, GMA
    - Change waveform conditions based on build features
  - Second arm – flexibility
    - SBI Plasma Arc DED System (being acquired)
      - Dual-wire feed
    - Auxiliary equipment: scanners, grinding, inspection
- Automated inter-pass temperature control
- Two axis positioner capable of building single- or double-sided build platform structures





# SBI Plasma Arc DED

- 350 Amp AC/DC Inverter System
  - 290 Amp DC 100% Duty
- Multifunctional plasma system:
  - Plasma joining and hardfacing
  - Plasma spot welding
  - Plasma powder welding
  - Plasma brazing
  - TIG welding (GTAW)
  - Plasma metal deposition (directed energy deposition) with wire and powder
- Single/dual hot wire & powder feed

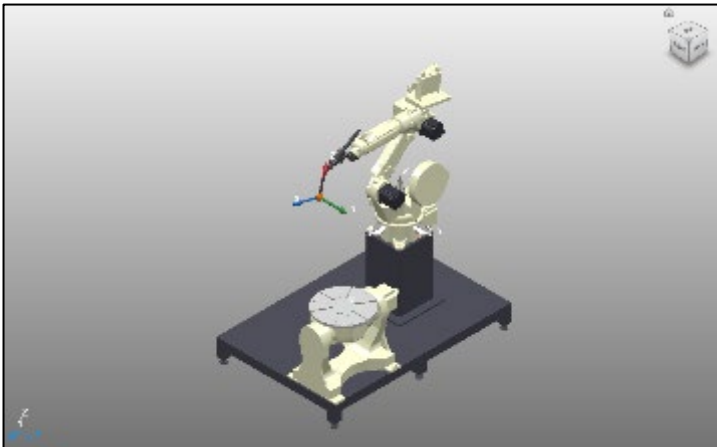
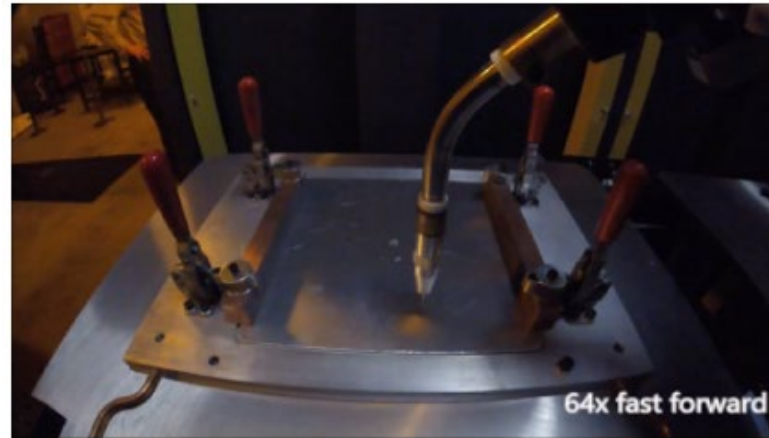


# EWI/OSU OTC Robotic DED Systems

Synchro-feed

100% CO<sub>2</sub>

No Spatter



- Two (2) OTC 8-axis GMA-P DED Systems
  - Synchro-Feed™ Robotic Welding
  - Welbee WB-P500L power source
  - Inter-pass temperature control
  - Two axis positioner
- Current Ma2JIC focus
  - ER5183 GMA-P DED
  - Walls & Block Procedures
  - 6- & 8-axis Builds



**Ma<sup>2</sup>JIC**  
MANUFACTURING & MATERIALS  
JOINING INNOVATION CENTER

# EWI/OSU Cloos Robotic Multi-process DED System

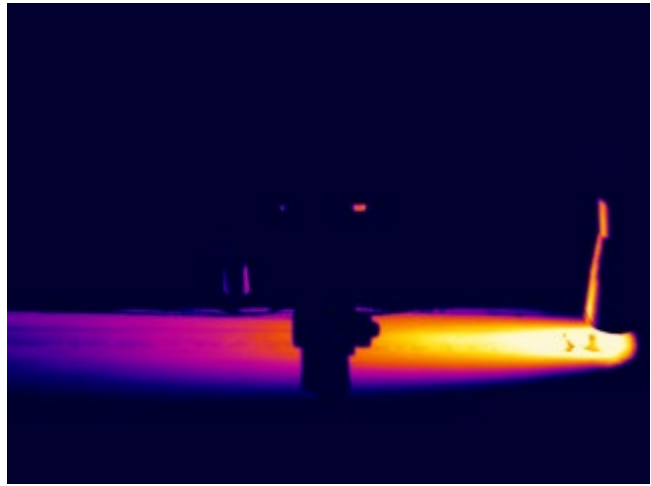
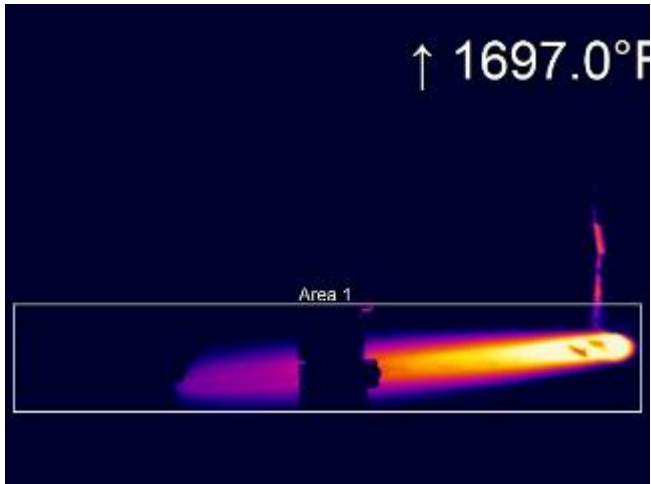
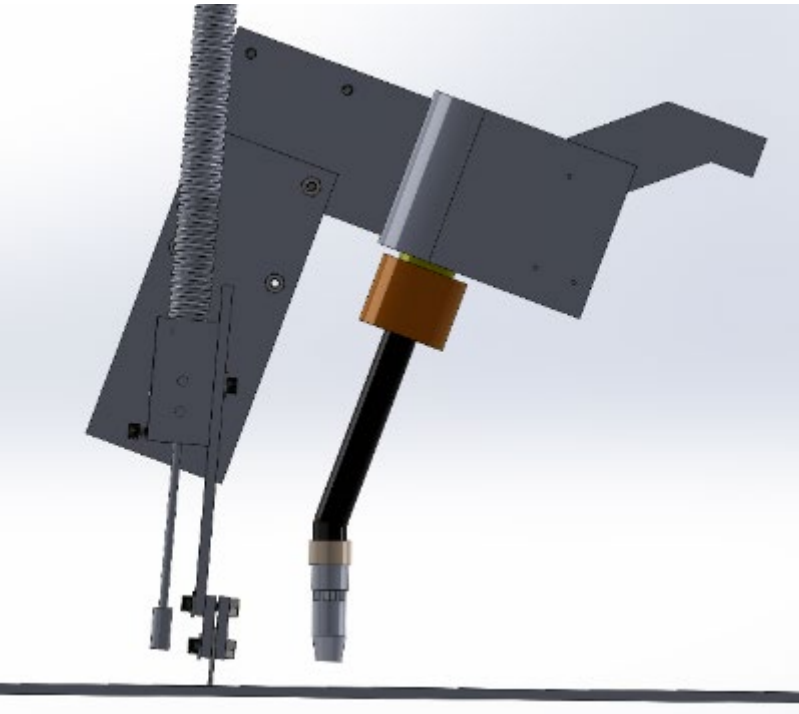
- Dual Process Test-bed
  - Motion, GMA, and Tandem GMA
  - High melting rate T-GMA control
  - Laser depth & IR sensors
  - 2-ton capacity double-sided builds
- Feature - cooling rate – property control
  - Cryogenic cooling support process
  - Maximum duty and build rate
- Adapt waveform conditions based on build conditions to max productivity and control properties.
- Current Ma2JIC focus
  - Adv. High Strength Steels



**Ma<sup>2</sup>JIC**  
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# Air Products In-situ Liquid Nitrogen Cryogenic Cooling (ILNCC)



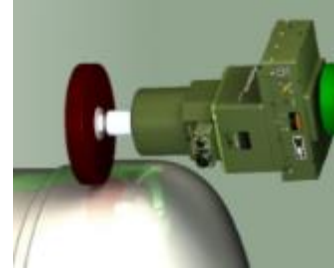


# Large-scale Multi-process Robotic Gantry DED System – Commission July 2020

## Pre-engineered (COTS) System

- 8-10-ft high x 14-ft wide x 30-ft long
- 60 Kg ABB IRB 4600 Robot
- Multi-process
  - Fronius CMT, Lincoln Power Wave
  - Arc, Laser, Hybrid laser-arc
  - PushCorp Grinder/brusher/burring spindle
- 11-axis w /1-ton tilt/turn positioner
- Sensor platform for development of quality control and part certification technologies
- Unique resource for prototyping metal DED AM structures and components

**System available for large-scale DED application development**



# Large-scale Multi-process Robotic Gantry DED System

## Welding Processes

- Welding systems
  - Fronius TPS 500i CMT system
    - Fronius WF 60i Robacta Drive CMT Torch
    - Fronius CU 1100i Water Cooler
  - Lincoln S500 system
    - Binzel ROBOWH-WC Torch
    - Lincoln Cool Arc 55 S Water Cooler
    - STT Power Wave module

- Binzel Torch Maintenance Station
  - Services Both Torch Types
- Binzel Torch Exchange Stations
- ABB Bullseye
- Additional Wire Clipper at Robot Base

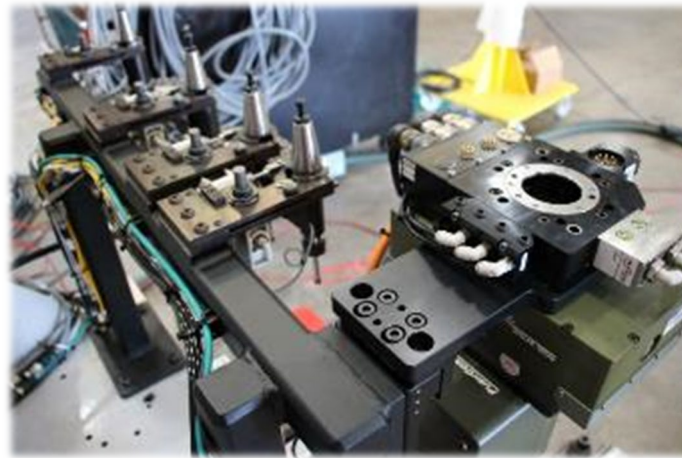




# Large-scale Multi-process Robotic Gantry DED System

## Metalworking processes

- PushCorp 5-HP spindle
  - AFD340 Active Compliance Device
  - BT30 Tool Changing Station
    - Grinding, burring, brushing
  - Miller Coolmate 3 Water Cooler
- ATI Tool Changer



# Large-scale Multi-process Robotic Gantry DED System

## Monitoring Sensors

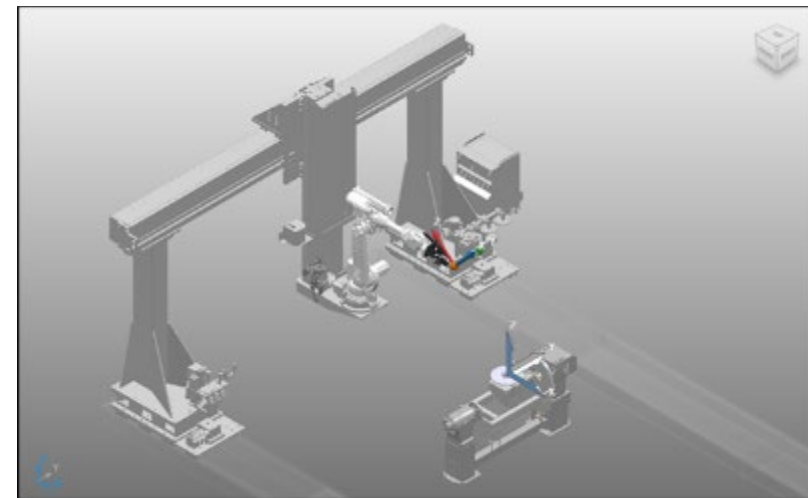
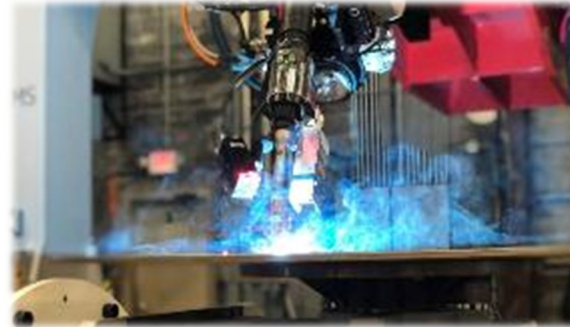
- Synchronized weld parameter data acquisition
- Melt Tools camera
  - Weld pool monitoring
- Micro-Epsilon TIM 640 Thermal Imaging Camera
  - Non-contact measurement of surface temperature from  $-4^{\circ}\text{F}$  to  $4442^{\circ}\text{F}$
  - Inter-pass Temperature control
- Binzel TH6D-GF Sensor
  - Seam tracking and finding
  - Profile measurement and documentation during DED AM
  - Used with both welding systems
    - Mount for Binzel Torch
    - Mount for Fronius Torch





# Pre-Engineered Large-scale Robotic Gantry DED Systems

- Digital-twin available for build simulations
- Post-processors solved for 9- & 11- axis
  - Large-scale single-sided builds
  - Large scale double-sided builds
- System Derivatives
  - Large/smaller work envelope
  - Head stock/tail stock – double-sided builds
  - High deposition arc DED packages
  - Laser DED packages
  - Digital manufacturing
    - DED, Welding, Cladding, Machining



# New Capabilities - Summary

- Established digital twin and post-processor for 7 robotic DED systems (1-Motoman, 3-Fanuc, 2-OTC, 1 ABB)
- Developed, integrated and installed large-scale robotic DED Test-bed (supplied by Navus/ABB)
- Developed 9- and 11-axis digital twin model & post-processor for large-scale robotic gantry DED system installed at EWI
- Developed DED procedure models for 308L stainless steel and nickel aluminum bronze
- Demonstrated single-sided integrated build platform standard qualification builds
- Built basic components of increasing complexity (coupler, propeller blade) with platform robotic DED systems
- Developed basic PowerMill Robotic DED training seminar
- Developed advanced PowerMill robotic DED training program
- Launching Autodesk Authorized Training Center (ATC)
- Building basic & advanced components of increasing complexity with gantry test-bed
- Offering (Navus) pre-engineered/standardized large-scale DED system(s) for industry acquisition
- Planning development of "Lights-out" support processes (thermal mgmt., auto-maintenance, quality monitoring & control, etc.)

# Ongoing Development Needs - Lights-out Technology

- Thermal management system
  - Infrared camera
  - Preheat/Inter-pass control
  - Forced cooling system and methods
  - Cooling rate control (long range)
- Hybrid Manufacturing/In-situ Clean Machining
  - 3-axis gantry milling for hard metals
    - Z-axis upgrade concept
  - Robotic grinding for hard metal
  - Robotic routing for soft metals
  - Start/stop contour grinding
  - Incremental feature grinding/milling
  - Clean Machining with In-situ Clean Cryogenic Cooling
- Automated torch maintenance
  - Torch cleaners
  - Wire cutter
  - Neck/tip changer
  - Cloos Sparematic auto nozzle and tip changer
  - Binzel neck changer station
- Process quality monitoring
  - Process behavior & parameter analysis
  - Pool behavior
  - Feature - cooling rate – property modeling
  - Dimensional data & management
- In-situ NDE
  - PowerInspect Software Suite
  - Vision processing
  - UT, ET, AET

# Ongoing Development Needs

- **Develop advanced large-scale builds and prototypes for candidate shipyard applications**
  - **Develop DED models for different materials and features**
    - **Demonstrate qualification builds and feature prototypes**
  - **Evaluate alternative DED processes (plasma arc, wire arc)**
- **Develop Part (Component) Verification Scheme Requirements**
  - *Technical Publication - NAVSEA Process Requirements for Metal Directed Energy Deposition*
  - **Develop DED AM operations and process prototypes for:**
    - **Part Verification Build Procedure(s) Workflow**
    - **Quality Assurance System**
    - **Process Control Plan**
    - **Training Plan**

*Accelerate shipyard implementation  
and impact*



# Questions

